## Semantics and Verification 2005

#### Lecture 1

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# Focus of the Course

- Study of mathematical models for the formal description and analysis of programs.
- Particular focus on parallel and reactive systems.
- Verification tools and implementation techniques underlying them.

# Overview of the Course

- Transition systems and CCS.
- Strong and weak bisimilarity, bisimulation games.
- Hennessy-Milner logic and bisimulation.
- Tarski's fixed-point theorem.
- Hennessy-Milner logic with recursively defined formulae.
- Timed automata and their semantics.
- Binary decision diagrams and their use in verification.
- Two mini projects.

# Mini Projects

- Verification of a communication protocol in CWB.
- Verification of an algorithm for mutual exclusion in UPPAAL.
- Pensum dispensation.

## Lectures

- Two guest lectures (G. Behrmann, K. G. Larsen).
- Ask questions.
- Take your own notes.
- Read the recommended literature as soon as possible after the lecture.

## **Tutorials**

- Regularly before each lecture.
- Supervised peer learning.
- Two classrooms, work in groups of 2 or 3 people.
- Print out the exercise list, bring literature and your notes.
- Feedback from teaching assistant on your request.
- Star exercises (\*) (part of the exam).

## Exam

- Individual and oral.
- Preparation time (star exercises).
- Pensum dispensation.

## Literature

- On-line literature.
- Compendiums (2004 + 2005, 141 kr).
- Best Reader Competition with award!

## Hints

- Check regularly the course web-page.
- Anonymous feedback form on the course web-page.
- Attend and actively participate during tutorials.
- Take your own notes.

## Aims of the Course

Present a general theory of reactive systems and its applications.

- Design.
- Specification.
- Verification (possibly automatic and compositional).

- Give the students practice in modelling parallel systems in a formal framework.
- ② Give the students skills in analyzing behaviours of reactive systems.
- Introduce algorithms and tools based on the modelling formalisms.

## Classical View

## Characterization of a Classical Program

Program transforms an input into an output.

Denotational semantics:
 a meaning of a program is a partial function

$$states \hookrightarrow states$$

- Nontermination is bad!
- In case of termination, the result is unique.

Is this all we need?

# Reactive systems

#### What about:

- Operating systems?
- Communication protocols?
- Control programs?
- Mobile phones?
- Vending machines?

# Reactive systems

### Characterization of a Reactive System

Reactive System is a system that computes by reacting to stimuli from its environment.

### Key Issues:

- communication and interaction
- parallelism

### Nontermination is good!

The result (if any) does not have to be unique.

# Analysis of Reactive Systems

### Questions

- How can we develop (design) a system that "works"?
- How do we analyze (verify) such a system?

### Fact of Life

Even short parallel programs may be hard to analyze.

# The Need for a Theory

### Conclusion

We need formal/systematic methods (tools), otherwise ...

- Intel's Pentium-II bug in floating-point division unit
- Ariane-5 crash due to a conversion of 64-bit real to 16-bit integer
- Mars Pathfinder
- ...

# Classical vs. Reactive Computing

	Classical	Reactive/Parallel
interaction	no	yes
nontermination	undesirable	often desirable
unique result	yes	no
semantics	$states \hookrightarrow states$	?

# How to Model Reactive Systems

### Question

What is the most abstract view of a reactive system (process)?

#### Answer

A process performs an action and becomes another process.

# Labelled Transition System

### Definition

A labelled transition system (LTS) is a triple  $(Proc, Act, \{\stackrel{a}{\longrightarrow} | a \in Act\})$  where

- Proc is a set of states (or processes),
- Act is a set of labels (or actions), and
- for every  $a \in Act$ ,  $\stackrel{a}{\longrightarrow} \subseteq Proc \times Proc$  is a binary relation on states called the transition relation.

We will use the infix notation  $s \stackrel{a}{\longrightarrow} s'$  meaning that  $(s, s') \in \stackrel{a}{\longrightarrow}$ .

Sometimes we distinguish the initial (or start) state.

# Sequencing, Nondeterminism and Parallelism

LTS explicitly focuses on interaction.

LTS can also describe:

- sequencing (a; b)
- choice (nondeterminism) (a + b)
- limited notion of parallelism (by using interleaving) (a|b)

# Binary Relations

#### Definition

A binary relation R on a set A is a subset of  $A \times A$ .

$$R \subseteq A \times A$$

Sometimes we write x R y instead of  $(x, y) \in R$ .

## Properties

- R is reflexive if  $(x, x) \in R$  for all  $x \in A$
- R is symmetric if  $(x, y) \in R$  implies that  $(y, x) \in R$  for all  $x, y \in A$
- R is transitive if  $(x, y) \in R$  and  $(y, z) \in R$  implies that  $(x, z) \in R$  for all  $x, y, z \in A$

## Closures

Let R, R' and R'' be binary relations on a set A.

### Reflexive Closure

R' is the reflexive closure of R if and only if

- $\bullet$   $R \subseteq R'$ ,
- $\bigcirc$  R' is reflexive, and
- R' is the smallest relation that satisfies the two conditions above, i.e., for any relation R":
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  - if  $R \subseteq R''$  and R'' is reflexive, then  $R' \subseteq R''$ .

## Closures

Let R, R' and R'' be binary relations on a set A.

### Symmetric Closure

R' is the symmetric closure of R if and only if

- $\bullet$   $R \subseteq R'$ ,
- $\bigcirc$  R' is symmetric, and
- **3** R' is the *smallest* relation that satisfies the two conditions above, i.e., for any relation R'':
  - if  $R \subseteq R''$  and R'' is symmetric, then  $R' \subseteq R''$ .

## Closures

Let R, R' and R'' be binary relations on a set A.

#### Transitive Closure

R' is the transitive closure of R if and only if

- $\bullet$   $R \subseteq R'$ ,
- $\bigcirc$  R' is transitive, and

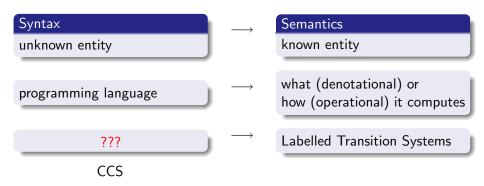
if 
$$R \subseteq R''$$
 and  $R''$  is transitive, then  $R' \subseteq R''$ .

# Labelled Transition Systems – Notation

Let  $(Proc, Act, \{\stackrel{a}{\longrightarrow} | a \in Act\})$  be an LTS.

- we extend  $\stackrel{a}{\longrightarrow}$  to the elements of  $Act^*$
- $\bullet \longrightarrow = \bigcup_{a \in Act} \xrightarrow{a}$
- $\bullet \longrightarrow^*$  is the reflexive and transitive closure of  $\longrightarrow$
- $s \stackrel{a}{\longrightarrow} \text{ and } s \stackrel{a}{\longrightarrow}$
- reachable states

# How to Describe LTS?



# Calculus of Communicating Systems

### **CCS**

Process algebra called "Calculus of Communicating Systems".

## Insight of Robin Milner (1989)

Concurrent (parallel) processes have an algebraic structure.

$$P_1$$
 op  $P_2$   $\Rightarrow$   $P_1$  op  $P_2$ 

# Process Algebra

### Basic Principle

- Define a few atomic processes (modelling the simplest process behaviour).
- ② Define compositionally new operations (building more complex process behaviour from simple ones).

### Example

- atomic instruction: assignment (e.g. x:=2 and x:=x+2)
- 2 new operators:
  - sequential composition  $(P_1; P_2)$
  - parallel composition  $(P_1 \parallel P_2)$

Now e.g. (x:=1  $\parallel$  x:=2); x:=x+2; (x:=x-1  $\parallel$  x:=x+5) is a process.

# CCS Basics (Sequential Fragment)

- Nil (or 0) process (the only atomic process)
- action prefixing (a.P)
- names and recursive definitions  $\stackrel{\text{def}}{=}$
- nondeterministic choice (+)

### This is Enough to Describe Sequential Processes

Any finite LTS can be (up to isomorphism) described by using the operations above.