Synthesizing Optimally Resilient Controllers

Joint work with Daniel Neider and Alexander Weinert

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Add disturbance edges (dashed) to classical safety game

- Only from Player 0 vertices
- Not under control of Player 1 nor equipped with fault model
- Instead: assumed to be "rare" events

Question: how many disturbances can Player 0 deal with?



Definition

The resilience of a vertex v is the largest k such that Player 0 has a strategy σ such that every play that

- starts in v,
- is consistent with σ , and
- has strictly less than k disturbances
- is winning for Player 0.



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Theorem (DNT'16)

The resilience of the vertices of a safety game G and a memoryless optimally resilient strategy for G are computable in polynomial time.







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Theorem (NWZ'18)

The resilience of the vertices of a parity game \mathcal{G} and a memoryless optimally resilient strategy for \mathcal{G} are computable in quasi-polynomial time.

Disturbances make games more interesting!



Disturbances can be desirable:

- From upper vertex, one disturbance takes Player 0 from her opponent's winning region to her own
- From the lower vertex, there is no such chance for recovery

Note that both vertices have resilience 0

Disturbances make games more interesting!



Tradeoff: disturbances vs. winning condition

- If odd colors are to be avoided, then the upper route is preferable (it takes two consecutive disturbances to reach 1)
- If disturbances are to be avoided, then the lower route is preferable (only one disturbance possible)

Note that both strategies witness all vertices having resilience $\boldsymbol{\omega}$

Disturbances make games more interesting!



Tradeoff: disturbances vs. memory

- The more memory Player 0 uses, the more she can avoid the risk of a fatal disturbance,
- but she has to take the risk infinitely often to satisfy the parity condition.