Optimal Bounds in Parametric LTL Games

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Motivation

Linear Temporal Logic (LTL) as specification language:

- Simple and variable-free syntax and intuitive semantics.
- Expressively equivalent to first-order logic on words.
- LTL model-checking routinely applied in industrial settings.

But LTL cannot express timing constraints.

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But LTL cannot express timing constraints. Possible remedies:

- Add $\mathbf{F}_{\leq k}$ for $k \in \mathbb{N}$. Problem: finding "right" k impracticable.
- Alur et. al, Kupferman et. al: add $\mathbf{F}_{\leq x}$ for variable x. Now:
 - does there exist a value x such that $\mathbf{F}_{\leq x}\varphi$ holds?
 - what is the best value x such that $\mathbf{F}_{\leq x}\varphi$ holds?

In Model-Checking: adding variable time bounds does not increase complexity.

Infinite Games

Arena $\mathcal{A} = (V, V_0, V_1, E)$:

- finite directed graph (V, E),
- $V_0 \subseteq V$ positions of Player 0 (circles),
- $V_1 = V \setminus V_0$ positions of Player 1 (squares).



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- Play: path $\rho_0 \rho_1 \cdots$ through \mathcal{A} .
- Strategy for Player *i*: σ : $V^*V_i \rightarrow V$ s.t. $(v, \sigma(wv)) \in E$.
- $\rho_0 \rho_1 \cdots$ consistent with $\sigma: \rho_{n+1} = \sigma(\rho_0 \cdots \rho_n)$ for all *n* s.t. $\rho_n \in V_i$.
- Finite-state strategy: implemented by finite automaton with output.

PLTL: Syntax and Semantics

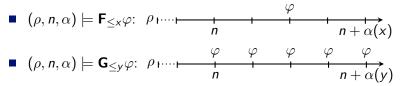
Parametric LTL: *p* atomic proposition, $x \in \mathcal{X}$, $y \in \mathcal{Y}$ $(\mathcal{X} \cap \mathcal{Y} = \emptyset)$. $\varphi ::= p | \neg p | \varphi \land \varphi | \varphi \lor \varphi | \mathbf{X}\varphi | \varphi \mathbf{U}\varphi | \varphi \mathbf{R}\varphi | \mathbf{F}_{\leq x}\varphi | \mathbf{G}_{\leq y}\varphi$

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Semantics w.r.t. variable valuation $\alpha \colon \mathcal{X} \cup \mathcal{Y} \to \mathbb{N}$:

■ As usual for LTL operators.

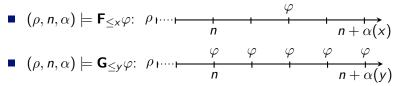


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Fragments:

- $PLTL_{F}$: no parameterized always operators $\mathbf{G}_{\leq y}$.
- $PLTL_G$: no parameterized eventually operators $F_{\leq x}$.

PLTL game: $\mathcal{G} = (\mathcal{A}, v_0, \varphi)$ with arena \mathcal{A} (labeled by $\ell \colon V \to 2^P$), initial vertex v_0 , and PLTL formula φ .

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Rules:

- all plays start in v_0 .
- Player 0 wins $\rho_0 \rho_1 \cdots$ w.r.t. α , if $(\ell(\rho_0)\ell(\rho_1)\cdots,\alpha) \models \varphi$.
- Player 1 wins $\rho_0 \rho_1 \cdots$ w.r.t. α , if $(\ell(\rho_0)\ell(\rho_1)\cdots,\alpha) \not\models \varphi$.

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- σ is winning strategy for Player *i* w.r.t. α , if every consistent play is winning for Player *i* w.r.t. α .
- Winning valuations for Player i

 $\mathcal{W}_i(\mathcal{G}) = \{ \alpha \mid \text{Player } i \text{ has winning strategy for } \mathcal{G} \text{ w.r.t. } \alpha \}$

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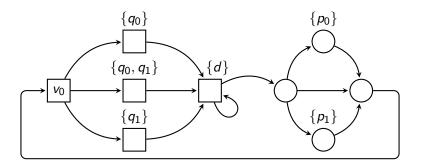
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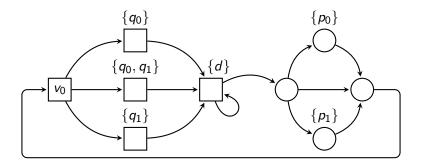
Lemma

Determinacy: $\mathcal{W}_0(\mathcal{G})$ is the complement of $\mathcal{W}_1(\mathcal{G})$.

An Example

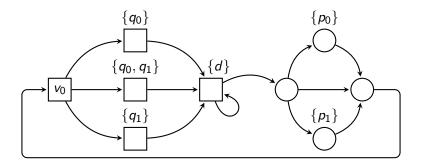


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$$\varphi_1 = \mathbf{FG}d \vee \bigwedge_{i \in \{0,1\}} \mathbf{G}(q_i \to \mathbf{F}p_i) : \mathcal{W}_1(\mathcal{G}_1) = \emptyset.$$

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• $\varphi_2 = \mathbf{FG}d \lor \bigwedge_{i \in \{0,1\}} \mathbf{G}(q_i \to \mathbf{F}_{\leq x_i}p_i) : \mathcal{W}_0(\mathcal{G}_2) = \emptyset.$

More Example Properties

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Finitary parity (Chatterjee, Henzinger, Horn):

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Finitary Streett (CHH):

$$\mathsf{FG}\bigwedge_{j=1}^k \left(\mathsf{R}_j \to \mathsf{F}_{\leq x} \mathsf{G}_j \right)$$

Decision Problems

- Membership: given \mathcal{G} , $i \in \{0, 1\}$, and α , is $\alpha \in \mathcal{W}_i(\mathcal{G})$?
- Emptiness: given \mathcal{G} and $i \in \{0, 1\}$, is $\mathcal{W}_i(\mathcal{G})$ empty?
- Finiteness: given \mathcal{G} and $i \in \{0, 1\}$, is $\mathcal{W}_i(\mathcal{G})$ finite?
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Adding parameterized operators does not increase complexity:

Theorem

All four decision problems are 2Exptime-complete.

Emptiness for $PLTL_{\mathbf{F}}$ games, i.e., only $\mathbf{F}_{\leq x}$ in φ .

- 1. Duplicate arena, color one copy red, the other green. Player 0 can change between copies after every move.
- **2.** Inductively replace every $F_{\leq x}\psi$ by

 $(\mathit{red} \rightarrow (\mathit{red} U(\mathit{green} U\psi))) \land (\mathit{green} \rightarrow (\mathit{green} U(\mathit{red} U\psi)))$

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Full PLTL and other problems: use monotonicity and duality of $F_{\leq x}$ and $G_{\leq y}$

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Theorem

Let \mathcal{G}_{F} be a $\operatorname{PLTL}_{\mathsf{F}}$ game with winning condition φ_{F} and let \mathcal{G}_{G} be a $\operatorname{PLTL}_{\mathsf{G}}$ game with winning condition φ_{G} . The following values (and winning strategies realizing them) can be computed in triply-exponential time.

1. $\min_{\alpha \in \mathcal{W}_0(\mathcal{G}_{\mathbf{F}})} \min_{x \in \operatorname{var}(\varphi_{\mathbf{F}})} \alpha(x).$

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- 4. $\max_{\alpha \in \mathcal{W}_0(\mathcal{G}_{\mathbf{G}})} \min_{y \in \operatorname{var}(\varphi_{\mathbf{G}})} \alpha(y).$

All values are at most doubly-exponential in the size of the game.

- 1. All problems reducible to $\min_{\alpha \in W_0(\mathcal{G})} \alpha(x)$ for φ with $\operatorname{var}(\varphi) = \{x\}.$
- Recall: algorithm for emptiness of W₀(G) yields doubly-exponential upper bound b on min_{α∈W₀(G)} α(x).
- **3.** For every $n \in [0, b]$ test whether *n* is optimum:

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- **3.** For every $n \in [0, b]$ test whether n is optimum:
 - **3.1** Translate φ into Büchi automaton \mathfrak{A}_{φ} (treat $\mathbf{F}_{\leq x}$ as \mathbf{F}).
 - **3.2** Add a counter with range [0, n] for every occurence of x to simulate semantics of $\mathbf{F}_{\leq x}$, obtain \mathfrak{A}'_{φ} of size $2^{|\varphi|} \cdot n^{|\varphi|}$.
 - **3.3** Determize \mathfrak{A}'_{φ} to obtain parity automation \mathfrak{P}_{φ} of size $2^{\mathcal{O}(|\varphi|^2 \cdot (2n)^{2|\varphi|})}$ and $\mathcal{O}(|\varphi| \cdot n^{|\varphi|})$ colors.
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Algorithm has triply exponential running time, since n is at most doubly-exponential.

Lower Bounds

For $\operatorname{PLTL}_{\boldsymbol{\mathsf{F}}}$ games: doubly-exponential lower bound

Theorem

For every $n \ge 1$, there exists a $\operatorname{PLTL}_{\mathsf{F}}$ game \mathcal{G}_n with winning condition φ_n with $|\mathcal{G}_n| \in \mathcal{O}(n^2)$ and $\operatorname{var}(\varphi_n) = \{x\}$ such that $\mathcal{W}_0(\mathcal{G}_n) \neq \emptyset$, but Player 1 wins \mathcal{G}_n with respect to every variable valuation α such that $\alpha(x) \le 2^{2^n}$.

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For PLTL_G games: doubly-exponential lower bound (by duality)

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Optimization problems in 2Exptime?

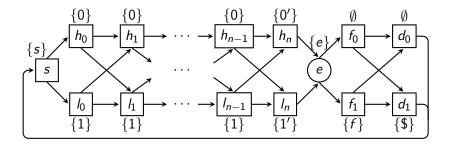
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The Game for the Lower Bounds



A Play in \mathcal{G}_n

We start in d_1 . The trace of a play looks as follows:

$$\{\$\}\{s\}\{b_0^0\}\cdots\{b_{n-1}^0\}\{b_n^0\}\{e\}F_0D_0 \\ \{s\}\{b_0^1\}\cdots\{b_{n-1}^1\}\{b_n^1\}\{e\}F_1D_1 \\ \{s\}\{b_0^2\}\cdots\{b_{n-1}^2\}\{b_n^2\}\{e\}F_2D_2\cdots$$

where

■
$$b_0^j, ..., b_{n-1}^j \in \{0, 1\} \Rightarrow$$
 encoding of $c_j \in \{0, 1, ..., 2^n - 1\}$
■ $b_n^j \in \{0', 1'\}$
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Infinitely many \$: primed bits encode numbers $d_{\ell} \in \mathbb{N}$

The Winning Condition

Recall: numbers c_j (adresses) and numbers d_ℓ whose bits are adressed by the c_j

There is an LTL formula ψ_1 which expresses:

- 1. Structure: Infinitely many \$
- **2.** Initialization: after each \$, the next c_j is zero.
- **3.** Increment: if $c_j < 2^n 1$, then $c_{j+1} = c_j + 1$.
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Lemma

$$\varphi_1 \Rightarrow d_\ell \in \{0, 1, \dots, 2^{2^n} - 1\}.$$

The Winning Condition, Part 2

$$\varphi_n = \psi_1 \to (\psi_f \wedge \psi_{\mathrm{err}} \wedge \mathbf{F}_{\leq x} f)$$

where

• ψ_f : exactly one f

• $\psi_{
m err}$: Player 0 used f to mark

• a single bit that is incorrectly updated from d_{ℓ} to $d_{\ell+1}$ (formula uses addresses to verify this), or

• a d_{ℓ} with $d_{\ell} = 2^{2^n} - 1$ (no primed 0 between two \$).

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 - a d_{ℓ} with $d_{\ell} = 2^{2^n} 1$ (no primed 0 between two \$).

Player 0 wins, since Player 1 has to reach $2^{2^n} - 1$ or has to introduce an increment-error. But this can take more than $2^{2^n} - 1$ moves using correct updates.