Parametric Linear Temporal Logics

Joint work with Peter Faymonville, Florian Horn, Wolfgang Thomas, and Nico Wallmeier

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Linear Temporal Logic (LTL) as specification language:

- Simple and variable-free syntax and intuitive semantics.
- Expressively equivalent to first-order logic on words.
- LTL model checking routinely applied in industrial settings.

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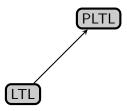
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 - Add **F**_{≤x} for variable x. Now: does there exist a valuation for x s.t. specification is satisfied?
- 2. LTL cannot express all ω -regular properties.
 - Many extensions that are equivalent to ω-regular languages: add regular expression-, grammar-, or automata-operators to LTL.

Overview



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Parametric LTL

Alur et al. '99: add parameterized operators to LTL $\varphi ::= p \mid \neg p \mid \varphi \land \varphi \mid \varphi \lor \varphi \mid \mathbf{X}\varphi \mid \varphi \mathbf{U}\varphi \mid \varphi \mathbf{R}\varphi \mid \mathbf{F}_{\leq x}\varphi \mid \mathbf{G}_{\leq y}\varphi$ with $x \in \mathcal{X}, y \in \mathcal{Y} \ (\mathcal{X} \cap \mathcal{Y} = \emptyset)$.

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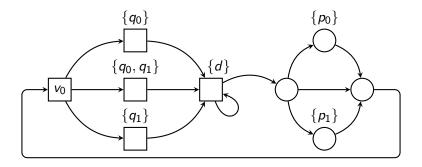
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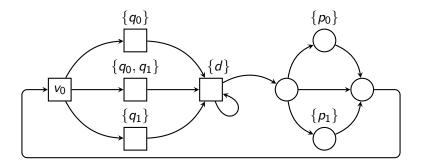
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Fragments:

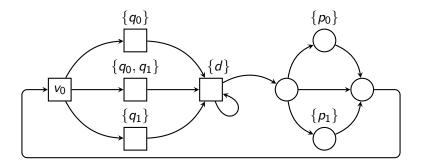
PLTL_F: no parameterized always operators $\mathbf{G}_{\leq y}$.

■ PLTL_G: no parameterized eventually operators $\mathbf{F}_{\leq x}$.

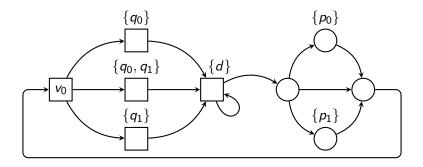




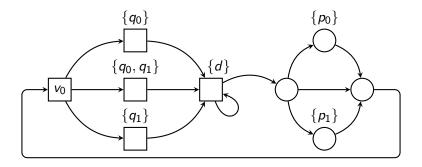
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- $\varphi_2 = \mathbf{FG}d \vee \bigwedge_{i \in \{0,1\}} \mathbf{G}(q_i \to \mathbf{F}_{\leq x_i}p_i)$: Player 1 wins w.r.t. every α .



 $W_i(\mathcal{G}) = \{ \alpha \mid \text{Player } i \text{ has winning strategy for } \mathcal{G} \text{ w.r.t. } \alpha \}$



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Lemma (Determinacy)

 $\mathcal{W}_0(\mathcal{G})$ is the complement of $\mathcal{W}_1(\mathcal{G})$.

Decision Problems

- Membership: given \mathcal{G} , $i \in \{0, 1\}$, and α , is $\alpha \in \mathcal{W}_i(\mathcal{G})$?
- Emptiness: given \mathcal{G} and $i \in \{0, 1\}$, is $\mathcal{W}_i(\mathcal{G})$ empty?
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Adding parameterized operators does not increase complexity:

Theorem (Z. '11)

All four decision problems are 2EXPTIME-complete.

Proof Sketch (Emptiness)

- 1. Replacing $\mathbf{G}_{\leq y}\psi$ by ψ preserves emptiness (monotonicity).
- 2. Apply alternating color technique (Kupferman et al. '06):
 - \blacksquare Add new proposition p and replace every $\mathbf{F}_{\leq \mathbf{x}} \psi$ by

$$(p \rightarrow p \mathbf{U}(\neg p \mathbf{U}\psi)) \land (\neg p \rightarrow \neg p \mathbf{U}(p \mathbf{U}\psi))$$

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- **3.** Emptiness for game with condition φ equivalent to Player 0 winning LTL game with condition $c(\varphi) \wedge \mathbf{GF}p \wedge \mathbf{GF}\neg p$, as finite state strategies bound distance between color changes.
- 4. Yields doubly-exponential upper bound.

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- **3.** $\max_{\alpha \in \mathcal{W}_0(\mathcal{G}_{\mathbf{G}})} \max_{y \in \operatorname{var}(\varphi_{\mathbf{G}})} \alpha(y).$

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Proof Sketch

• $\min_{\alpha \in \mathcal{W}_0(\mathcal{G}_F)} \max_{x \in var(\varphi_F)} \alpha(x)$ for $PLTL_F$ -formula φ_F .

- 1. Replacing every variable by z preserves optimum (monotonicity).
- 2. Doubly-exponential upper bound on optimum.
- 3. Models of φ w.r.t. α recognized by deterministic parity automaton of triply-exponential size, provided $\alpha(z)$ is at most doubly-exponential.
- 4. Thus, $\alpha \in \mathcal{W}_0(\mathcal{G}_F)$ can be decided in triply-exponential time.
- 5. Run binary search over doubly-exponential search space.

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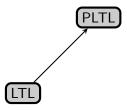
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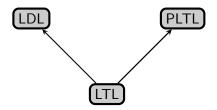
Note:

Doubly-exponential lower bound on optimum rules out doublyexponential running time for this algorithm.

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Linear Dynamic Logic

Vardi '11: Another extension of LTL expressing exactly the ω -regular languages: use PDL-like operators

$$\varphi ::= p \mid \neg p \mid \varphi \land \varphi \mid \varphi \lor \varphi \mid \langle r \rangle \varphi \mid [r] \varphi$$
$$r ::= \phi \mid \varphi? \mid r + r \mid r; r \mid r^*$$

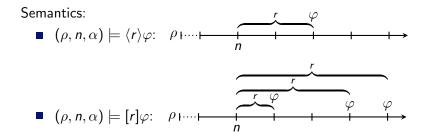
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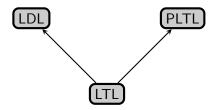
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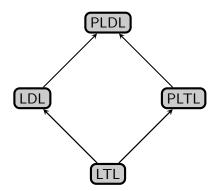
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We are interested in same decision problems as for PLTL

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as well as the optimization problems.

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1. Eliminate $[r]_{\leq y}\psi$:

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- $\langle r \rangle_{cc} \psi$: as for $\langle r \rangle \psi$, but take intersection of \mathfrak{A}_r and automaton checking for at most one color change.

Results for LDL

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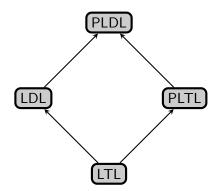
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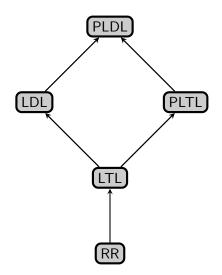
PLDL optimization problems are solvable in

- polynomial space for model checking, and
- triply-exponential time for games.

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Corollary

- Finite-state winning strategies of size $k2^{k+1}$ for both players.
- Solvable in EXPTIME.

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, and
 $\operatorname{wt}_{j}(wv) = \begin{cases} 0 \\ \end{cases}$

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Goal:

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Prove that optimal winning strategies exist and are computable.

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Main Theorem

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Optimal strategies for RR games exist, are effectively computable, and finite-state.

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- **2.** Expand arena by keeping track of waiting time vectors up to bound from 1.). RR-values equal to mean-payoff condition.
 - Optimal strategy for mean-payoff yields optimal strategy for RR game.

Dickson's Lemma

Dickson pair: $((x_1, \ldots, x_k), (y_1, \ldots, y_k)) \in \mathbb{N}^k$ s.t. $x_j \leq y_j$ for all j. Lemma (Dickson '13)

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Waiting time vectors are special:

- either increment, or
- reset to zero.

Lemma

There is a function $b(|\mathcal{A}|, k) \in \mathcal{O}(2^{2^{|\mathcal{A}| \cdot k+2}})$ such that every play infix of length $b(|\mathcal{A}|, k)$ has a dickson pair.

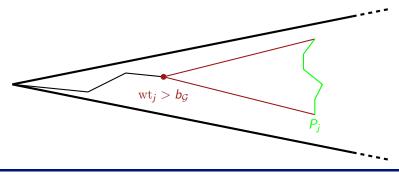
We have σ with $val(\sigma, v) \leq \sum_{j=1,...,k} |\mathcal{A}| k 2^k =: b_{\mathcal{G}}$ for all $v \in W_0(\mathcal{G})$.

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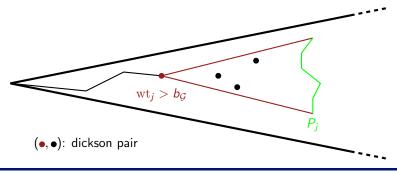
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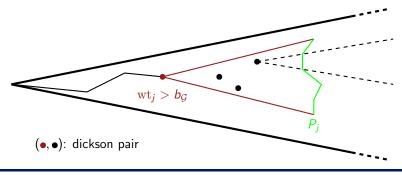
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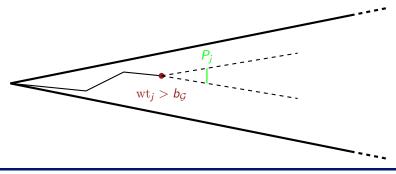
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$$t_{\max_i} = \operatorname{val}_{\mathcal{G}} + b(|\mathcal{A}|, k-1).$$

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Theorem

Optimal strategy for mean-payoff game can be translated into optimal strategy for RR game.

