

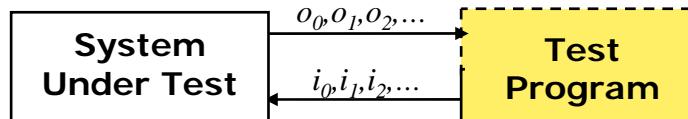


Model-Based Testing

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- The diagram shows two models enclosed in dashed boxes: a 'System Model' on the left and an 'Environment Model' on the right. The 'System Model' contains three states connected by transitions. The 'Environment Model' also contains states and transitions. An 'Output' arrow points from the System Model to the Environment Model, and an 'Input' arrow points from the Environment Model back to the System Model.
- **Input:** Timed automata model of system and environment
 - Test-suite generation algorithm
 - **Output:**
 - Test input/output sequence $\sigma_{\phi p} = i_0, i_1, i_2, \dots$
 - Test suite $T = \{\sigma_1, \dots, \sigma_n\}$, minimized w.r.t global time or global length



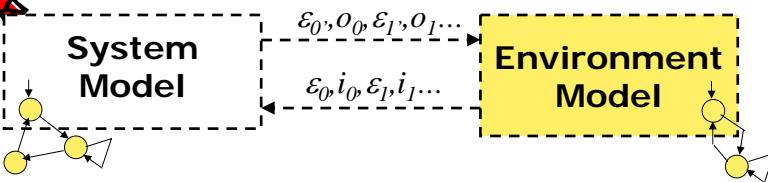
Testing Verdict



- Test specification $\sigma_{\phi p} = i_0, i_1, i_2, \dots$
- Test in/output $\delta_{\phi p} = i_0, o_0, i_1, o_1, i_2, i_3, \dots$
- **Test Verdict:**
 - OK, if $\delta_{\phi p} = i_0, o_0, i_1, o_1, i_2, i_3, \dots$ run of system model
 - NOK, otherwise



Testing Real-Time Systems



- Test input sequence $\sigma_{\phi p} = \varepsilon_0, i_0, \varepsilon_1, i_1, \varepsilon_2, i_2, \dots$
- Test in/output $\delta_{\phi p} = \varepsilon_0, i_0, \varepsilon_1, o_0, \varepsilon_1, i_1, o_1, \dots$
- Test Verdict:
 - OK, if $\delta_{\phi p} = \varepsilon_0, i_0, \varepsilon_1, o_0, \varepsilon_1, i_1, o_1, \dots$ run of system model
 - NOK, otherwise
- Timed Automata?



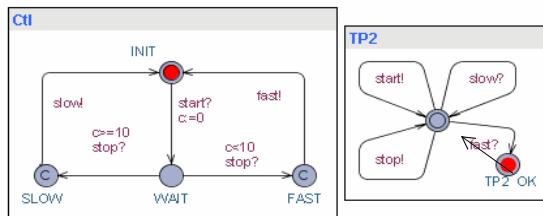
Controllable Timed Automata

- **Input Enabled:** all inputs can always be accepted
- **Output Urgent:** enabled outputs will occur immediately
- **Determinism:** two transitions with same input/output leads to the same state
- **Isolated Outputs:** if an output is enabled, no other output is enabled



Test Purpose Generation

- Generate input sequence for a single test purpose
- Reachability analysis
- Example: "fast" output can be sent by system

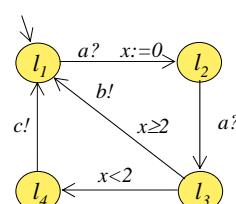


- TP2.OK reachable?
- Test input: **start!.delay(0).stop!.delay(0).fast?**



Coverage Based Test Generation

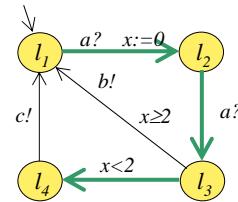
- Systematic testing
- Coverage measurement
- Examples:
 - Location coverage,
 - Edge coverage,
 - Definition/use pair coverage





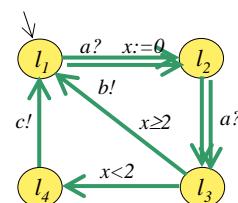
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Coverage Based Test Generation

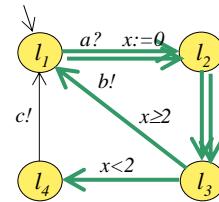
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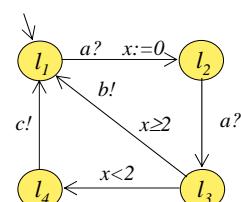
Coverage Based Test Generation

- Systematic testing
- Cover measurement
- Examples:
 - Location Coverage,
 - Edge Coverage,
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Coverage Based Test Generation

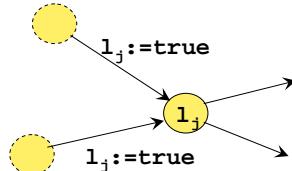
- Systematic testing
- Cover measurement
- Examples:
 - Locations coverage,
 - Edge coverage,
 - Definition/use pair coverage
 - All Definition/Use pairs
- Generated by modified model-checking algorithm in UPPAAL





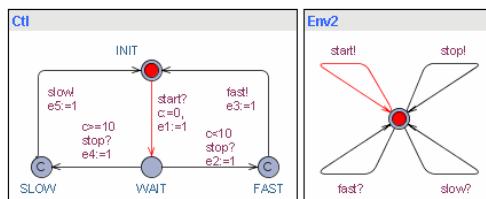
Location Coverage

- Test sequence traversing all locations
- Encoding:
 - Enumerate locations l_0, \dots, l_n
 - Add an auxiliary variable l_i for each location
 - Label each ingoing edge to location i $l_i := \text{true}$
 - Mark initial visited $l_0 := \text{true}$
- Check: $\text{EF}(l_0 = \text{true} \wedge \dots \wedge l_n = \text{true})$



Edge Coverage

- Test sequence traversing all edges
- Encoding:
 - Enumerate edges e_0, \dots, e_n
 - Add auxiliary variable e_i for each edge
 - Label each edge $e_i := \text{true}$
- Check: $\text{EF}(e_0 = \text{true} \wedge \dots \wedge e_n = \text{true})$

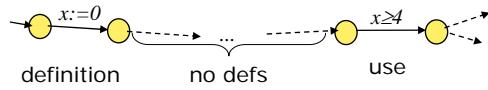




Definition/Use Pair Coverage

➤ Dataflow coverage technique

➤ Def/use pair of variable x :



➤ Encoding:

- $v_d \in \{ \text{false} \} \cup \{ e_0, \dots, e_n \}$, initially false
- Boolean array du of size $|E| \times |E|$
- At definition on edge i : $v_d := e_i$
- At use on edge j : if(v_d) then $du[v_d e_j] := \text{true}$

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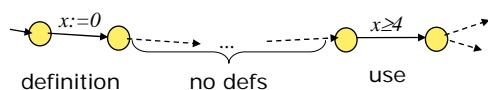
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Definition/Use Pair Coverage

➤ Dataflow coverage technique

➤ Def/use pair of variable x :



➤ Encoding:

- $v_d \in \{ \text{false} \} \cup \{ e_0, \dots, e_n \}$, initially false
- Boolean array du of size $|E| \times |E|$
- At definition on edge i : $v_d := e_i$
- At use on edge j : if(v_d) then $du[v_d e_j] := \text{true}$

du:

0				$n-1$
0				
i				
				$n-1$
				j

➤ Check:

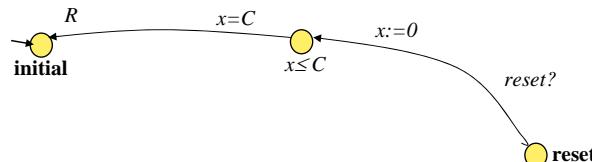
- EF(all $du[i,j] = \text{true}$)





Test Suite Generation

- In general a set of test cases is need to cover a test criteria
- Add global reset of SUT and environment model and associate a cost (of system reset)



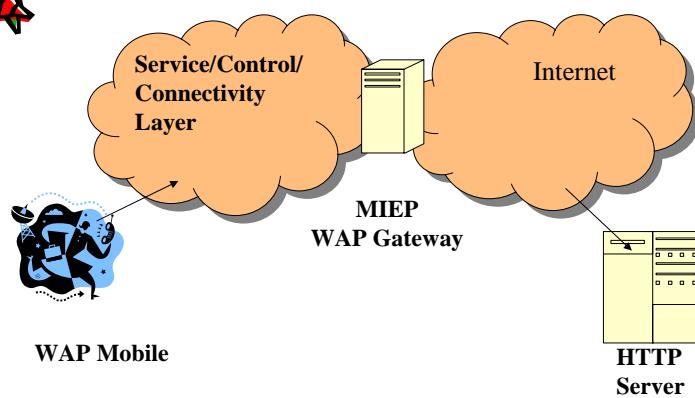
- Same encodings and min-cost reachability
- Test sequence $\sigma = \mathcal{E}_0, i_0, \dots, \mathcal{E}_l, i_l, \text{reset } \underbrace{\mathcal{E}_2, i_2, \dots, \mathcal{E}_0}_{\sigma_i}, i_0, \text{reest}, \mathcal{E}_l, i_l, \mathcal{E}_2, i_2, \dots$
- Test suite $T = \{ \sigma_1, \dots, \sigma_n \}$ with minimum cost



CoVer Tool

- Extension of UPPAAL
 - Graphical user interface
 - Timed Automata models
 - Symbolic on-the-fly algorithms
- Graphical input language for coverage criteria, a.k.a. Observers
- Generation of test specifications

Application w. Ericsson



- Automatic generation of test programs
- Systematic tests with coverage